

Asymptotic distribution of least square estimators for linear models with dependent errors

Emmanuel Caron¹

<http://ecaron.perso.math.cnrs.fr>

Directeurs de thèse: Jérôme Dedecker (MAP5), Bertrand Michel (LMJL)

18 Septembre 2018

¹Ecole Centrale Nantes, Laboratoire de Mathématiques Jean Leray UMR 6629, 1
Rue de la Noë, 44300 Nantes. **Email:** emmanuel.caron@ec-nantes.fr

Sommaire

- 1 Framework
 - 2 Hannan's theorem
 - 3 Estimation of the covariance matrix
 - 4 Tests and Simulations
- Bibliography

Sommaire

- 1 Framework
- 2 Hannan's theorem
- 3 Estimation of the covariance matrix
- 4 Tests and Simulations
Bibliography

Linear Regression Model

Linear Regression model:

$$Y = X\beta + \epsilon,$$

- X is a design, random or not, size $[n \times p]$
- Y is a n random vector
- β is a p vector of unknown parameters
- ϵ are the errors, $\epsilon \in \mathbb{R}^n$. The error process is independent of the design X .

Usual assumptions:

- the errors are i.i.d.
- $\mathbb{E}(\epsilon) = 0$ and $Var(\epsilon) = \sigma^2 I_n$
- Sometimes, $\epsilon \sim \mathcal{N}(0, \sigma^2 I_n)$

Least Square Estimator

$$\hat{\beta} = \operatorname{argmin}_{\beta \in \mathbb{R}^p} \|Y - X\beta\|_2^2 = (X^t X)^{-1} X^t Y.$$

- $\hat{Y} = X\hat{\beta}$: Orthogonal Projection of Y on $\mathcal{M}_X = \operatorname{Vect}\{X_{\cdot,1}, \dots, X_{\cdot,p}\}$
- Residual vector: $\hat{\epsilon} = Y - \hat{Y} = Y - X\hat{\beta} \in \mathcal{M}_X^\perp$
- $\hat{\sigma}^2 = \frac{\|\hat{\epsilon}\|_2^2}{n-p}$.

Distribution of the LSE in the i.i.d. case:

- Gaussian Case: $\hat{\beta} \sim \mathcal{N}(\beta, \sigma^2(X^t X)^{-1})$
- Non-Gaussian Case: $D(n)(\hat{\beta} - \beta) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}(0, \sigma^2 Q^{-1})$.

Goals and Plan

Main Goal : Remove the independence hypothesis and correct the results on the linear regression model in a very general framework

Plan :

- 1 Hannan's Theorem (1973) [4]: convergence of the LSE in the stationary case under very mild conditions
- 2 Estimation of the covariance matrix
- 3 Applications with Fisher's tests

Stationarity

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space. $(\epsilon_i)_{i \in \mathbb{Z}}$ is an error process defined on $(\Omega, \mathcal{F}, \mathbb{P})$, supposed strictly stationary, with zero mean, and $\epsilon_0 \in \mathbb{L}^2$.

Definition : Strict Stationarity

A stochastic process $(\epsilon_i)_{i \in \mathbb{Z}}$ is said to be strictly stationary if the joint distributions of $(\epsilon_{t_1}, \dots, \epsilon_{t_k})$ and $(\epsilon_{t_1+h}, \dots, \epsilon_{t_k+h})$ are the same for all positive integers k and for all $t_1, \dots, t_k, h \in \mathbb{Z}$.

Let $(\mathcal{F}_i)_{i \in \mathbb{Z}}$ be a non-decreasing filtration on $(\Omega, \mathcal{F}, \mathbb{P})$ (Example: $\mathcal{F}_i = \sigma(\epsilon_k, k \leq i)$).

We always suppose that $\mathcal{F}_{-\infty} = \bigcap_{i \in \mathbb{Z}} \mathcal{F}_i$ is trivial, and ϵ_0 \mathcal{F}_{∞} -measurable.

Spectral density

Autocovariance function of the error process:

$$\gamma(k) = \text{Cov}(\epsilon_m, \epsilon_{m+k}) = \mathbb{E}(\epsilon_m \epsilon_{m+k}),$$

and the covariance matrix: $\Gamma_n = [\gamma(j-l)]_{1 \leq j, l \leq n}$.

Let f be the associated spectral density, $\lambda \in [-\pi, \pi]$:

$$\gamma(k) = \int_{-\pi}^{\pi} e^{ik\lambda} f(\lambda) d\lambda,$$

$$f(\lambda) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \gamma(k) e^{ik\lambda}.$$

Sommaire

- 1 Framework
 - 2 **Hannan's theorem**
 - 3 Estimation of the covariance matrix
 - 4 Tests and Simulations
- Bibliography

Hannan's condition on the error process

Given the design X , Hannan has proved a CLT in the stationary case for the usual LSE $\hat{\beta}$ under very mild conditions.

- $\forall j \in \mathbb{Z}$ and $\forall Z \in \mathbb{L}^2(\Omega)$: $P_j(Z) = \mathbb{E}(Z|\mathcal{F}_j) - \mathbb{E}(Z|\mathcal{F}_{j-1})$.
- **Hannan's condition** on the error process:

$$\sum_{i \in \mathbb{Z}} \|P_0(\epsilon_i)\|_{\mathbb{L}^2} < +\infty.$$

This implies: $\sum_k |\gamma(k)| < +\infty$.

Hannan's condition is satisfied for most of short-range dependent processes.

Examples which verify Hannan's condition

- Linear Processes (Dedecker, Merlevède, Vólny (2007) [2])
- Functions of linear processes ([2])
- Conditions à la Gordin ([2])
- Framework of Wu (Wu (2005) [5])
- Weakly dependent sequences (Dedecker-Prieur (2004) [3], Caron-Dede (2017) [1])

Hannan's conditions on the design

- Let $X_{\cdot,j}$ be the column j of the matrix X , $j \in \{1, \dots, p\}$:

$$d_j(n) = \|X_{\cdot,j}\|_2 = \sqrt{\sum_{i=1}^n x_{i,j}^2},$$

and let $D(n)$ be the diagonal matrix with diagonal term $d_j(n)$.

- Conditions on the design:**

$$\forall j \in \{1, \dots, p\}, \quad \lim_{n \rightarrow \infty} d_j(n) = \infty \quad a.s.,$$

$$\forall j \in \{1, \dots, p\}, \quad \lim_{n \rightarrow \infty} \frac{\sup_{1 \leq i \leq n} |x_{i,j}|}{d_j(n)} = 0 \quad a.s.,$$

and the following limits exist:

$$\forall j, l \in \{1, \dots, p\}, \quad \rho_{j,l}(k) = \lim_{n \rightarrow \infty} \sum_{m=1}^{n-k} \frac{x_{m,j} x_{m+k,l}}{d_j(n) d_l(n)} \quad a.s.$$

We define the $p \times p$ matrix $R(k)$:

$$R(k) = [\rho_{j,l}(k)] = \int_{-\pi}^{\pi} e^{ik\lambda} F_X(d\lambda) \quad a.s.,$$

where F_X is the spectral measure associated with the matrix $R(k)$.

Moreover, we suppose:

$$R(0) > 0 \quad a.s.$$

Then let F and G be the matrices:

$$F = \frac{1}{2\pi} \int_{-\pi}^{\pi} F_X(d\lambda) \quad a.s.,$$

$$G = \frac{1}{2\pi} \int_{-\pi}^{\pi} F_X(d\lambda) \otimes f(\lambda) \quad a.s.$$

Theorem (Hannan (1973) [4])

Under the previous conditions, for all bounded continuous function f :

$$\mathbb{E} \left(f \left(D(n)(\hat{\beta} - \beta) \right) \middle| X \right) \xrightarrow[n \rightarrow \infty]{a.s.} \mathbb{E} \left(f(Z) \middle| X \right),$$

where the distribution of Z given X is: $\mathcal{N}(0, F^{-1}GF^{-1})$.

Furthermore we have the convergence of second order moment:

$$\mathbb{E} \left(D(n)(\hat{\beta} - \beta)(\hat{\beta} - \beta)^t D(n)^t \middle| X \right) \xrightarrow[n \rightarrow \infty]{a.s.} F^{-1}GF^{-1},$$

Remark

Let us notice that, by the dominated convergence theorem, we have for any bounded continuous function f :

$$\mathbb{E} \left(f \left(D(n)(\hat{\beta} - \beta) \right) \right) \xrightarrow[n \rightarrow \infty]{} \mathbb{E} (f(Z)),$$

Sommaire

- 1 Framework
- 2 Hannan's theorem
- 3 Estimation of the covariance matrix
- 4 Tests and Simulations
Bibliography

To obtain confidence regions or test procedures, one needs to estimate the limiting covariance matrix $F^{-1}GF^{-1}$. By Hannan, we have:

$$\mathbb{E} \left(D(n)(\hat{\beta} - \beta)(\hat{\beta} - \beta)^t D(n)^t \middle| X \right) \xrightarrow[n \rightarrow \infty]{a.s.} F^{-1}GF^{-1},$$

and:

$$\mathbb{E} \left(D(n)(\hat{\beta} - \beta)(\hat{\beta} - \beta)^t D(n)^t \middle| X \right) = D(n)(X^t X)^{-1} X^t \Gamma_n X (X^t X)^{-1} D(n),$$

with $\Gamma_n = [\gamma(j-l)]_{1 \leq j, l \leq n}$ (covariance matrix of the error process).
 Then we need an estimator of Γ_n .

Let us first consider a preliminary random matrix:

$$\widehat{\Gamma}_{n,h_n} = \left[K \left(\frac{j-l}{h_n} \right) \hat{\gamma}_{j-l} \right]_{1 \leq j, l \leq n}$$

with:

$$\hat{\gamma}_k = \frac{1}{n} \sum_{j=1}^{n-|k|} \epsilon_j \epsilon_{j+|k|}, \quad 0 \leq |k| \leq (n-1).$$

The function K is a kernel such that:

- K is nonnegative, symmetric, and $K(0) = 1$
- K has compact support
- the fourier transform of K is integrable.

The sequence of positive reals h_n is such that $h_n \xrightarrow[n \rightarrow \infty]{} \infty$ and $\frac{h_n}{n} \xrightarrow[n \rightarrow \infty]{} 0$.

In our context, $(\epsilon_i)_{i \in \{1, \dots, n\}}$ is not observed. Only the residuals are available:

$$\hat{\epsilon}_i = Y_i - (x_i)^t \hat{\beta} = Y_i - \sum_{j=1}^p x_{i,j} \hat{\beta}_j,$$

because only the data Y and the design X are observed. Consequently, we consider the following estimator of Γ_n :

$$\hat{\Gamma}_{n, h_n}^* = \left[K \left(\frac{j-l}{h_n} \right) \hat{\gamma}_{j-l}^* \right]_{1 \leq j, l \leq n}$$

where:

$$\hat{\gamma}_k^* = \frac{1}{n} \sum_{j=1}^{n-|k|} \hat{\epsilon}_j \hat{\epsilon}_{j+|k|}, \quad 0 \leq |k| \leq (n-1).$$

To estimate the asymptotic covariance matrix $F^{-1}GF^{-1}$, we use the estimator:

$$C_n = D(n)(X^t X)^{-1} X^t \widehat{\Gamma}_{n, h_n}^* X (X^t X)^{-1} D(n).$$

Let us denote by C the matrix $F^{-1}GF^{-1}$ and the coefficients of the matrices C_n and C are respectively denoted by $c_{n,(j,l)}$ and $c_{j,l}$, for all j, l in $1, \dots, p$.

Consistence

Theorem (C. (2018), submitted)

Let h_n be a sequence of positive reals such that $h_n \rightarrow \infty$ as n tends to infinity, and:

$$h_n \mathbb{E} \left(|\epsilon_0|^2 \left(1 \wedge \frac{h_n}{n} |\epsilon_0|^2 \right) \right) \xrightarrow{n \rightarrow \infty} 0.$$

Then, under the assumptions of Hannan's Theorem, the estimator C_n is consistent, that is for all j, l in $1, \dots, p$:

$$\mathbb{E} \left(|c_{n,(j,l)} - c_{j,l}| \middle| X \right) \xrightarrow{n \rightarrow \infty} 0$$

Corollary

Under the same conditions, the estimator C_n converges in probability to C as n tends to infinity.

Sketch of the proof

Let $V(X)$ be the matrix $\mathbb{E} \left(D(n)(\hat{\beta} - \beta)(\hat{\beta} - \beta)^t D(n)^t \middle| X \right)$, and let $v_{j,l}$ be its coefficients. By the triangle inequality, $\forall j, l \in \{1, \dots, p\}$:

$$|c_{n,(j,l)} - c_{j,l}| \leq |v_{j,l} - c_{j,l}| + |c_{n,(j,l)} - v_{j,l}|.$$

Thanks to Hannan's Theorem:

$$\lim_{n \rightarrow \infty} \mathbb{E} \left(|v_{j,l} - c_{j,l}| \middle| X \right) = 0, \quad a.s.$$

Then it remains to prove that:

$$\lim_{n \rightarrow \infty} \mathbb{E} \left(|c_{n,(j,l)} - v_{j,l}| \middle| X \right) = 0, \quad a.s.$$

Thanks to the convergence of $D_n(X^t X)^{-1} D_n$ to $R(0)^{-1}$, it is sufficient to consider the matrices:

$$V'_n = D_n^{-1} X^t \Gamma_n X D_n^{-1}, \quad C'_n = D_n^{-1} X^t \widehat{\Gamma}_{n,h_n}^* X D_n^{-1}.$$

We know that $\Gamma_n = \sum_{k=-n+1}^{n-1} \gamma(k) J_n^{(k)}$. Thus we have:

$$D(n)^{-1} X^t \Gamma_n X D(n)^{-1} = \sum_{k=-n+1}^{n-1} \gamma(k) B_{k,n}$$

$$D(n)^{-1} X^t \hat{\Gamma}_{n,h_n}^* X D(n)^{-1} = \sum_{k=-n+1}^{n-1} K\left(\frac{k}{h_n}\right) \hat{\gamma}_k^* B_{k,n}$$

with $B_{k,n} = D(n)^{-1} X^t J_n^{(k)} X D(n)^{-1}$.

$$\left| c'_{n,(j,l)} - v'_{j,l} \right| = \left| \sum_{k=-n+1}^{n-1} \left(K\left(\frac{k}{h_n}\right) \hat{\gamma}_k^* - \gamma(k) \right) b_{j,l}^{k,n} \right|$$

where $b_{j,l}^{k,n}$ is the coefficient (j, l) of the $B_{k,n}$ matrix.

Then:

$$\sum_{k=-n+1}^{n-1} \left(K \left(\frac{k}{h_n} \right) \hat{\gamma}_k^* - \gamma(k) \right) B_{k,n} = \int_{-\pi}^{\pi} (f_n^*(\lambda) - f(\lambda)) g_n(\lambda) (d\lambda)$$

with:

$$g_n(\lambda) = \frac{1}{2\pi} \sum_{k=-(n-1)}^{n-1} e^{ikx} B_{k,n}.$$

in such a way that the matrices $B_{k,n}$ are the Fourier coefficients of the function $g_n(\lambda)$:

$$B_{k,n} = \int_{-\pi}^{\pi} e^{ik\lambda} g_n(\lambda) d\lambda.$$

We have:

$$\begin{aligned} & \mathbb{E} \left(\left| \int_{-\pi}^{\pi} (f_n^*(\lambda) - f(\lambda)) [g_n(\lambda)]_{j,l} d\lambda \right| \middle| X \right) \\ & \leq \sup_{\lambda \in [-\pi, \pi]} \mathbb{E} \left(|f_n^*(\lambda) - f(\lambda)| \middle| X \right) \int_{-\pi}^{\pi} |[g_n(\lambda)]_{j,l}| d\lambda \end{aligned}$$

Proof: Spectral density estimate

And:

$$\begin{aligned} \sup_{\lambda \in [-\pi, \pi]} \mathbb{E} \left(|f_n^*(\lambda) - f(\lambda)| \mid X \right) & \int_{-\pi}^{\pi} |[g_n(\lambda)]_{j,l}| d\lambda \\ & \leq \sup_{\lambda \in [-\pi, \pi]} \mathbb{E} \left(|f_n^*(\lambda) - f(\lambda)| \mid X \right). \end{aligned}$$

Then consider the following estimator:

$$f_n^*(\lambda) = \frac{1}{2\pi} \sum_{|k| \leq n-1} K \left(\frac{|k|}{h_n} \right) \hat{\gamma}_k^* e^{ik\lambda}, \quad \lambda \in [-\pi, \pi],$$

where:

$$\hat{\gamma}_k^* = \frac{1}{n} \sum_{j=1}^{n-|k|} \hat{\epsilon}_j \hat{\epsilon}_{j+|k|}, \quad 0 \leq |k| \leq (n-1).$$

Theorem (C.-Dede (2017) [1], submitted)

Let h_n be a sequence of positive integers such that $h_n \rightarrow \infty$ as n tends to infinity, and: $h_n \mathbb{E} \left(|\epsilon_0|^2 \left(1 \wedge \frac{h_n}{n} |\epsilon_0|^2 \right) \right) \xrightarrow[n \rightarrow \infty]{} 0$. Then, under the assumptions of Hannan's Theorem:

$$\sup_{\lambda \in [-\pi, \pi]} \|f_n^*(\lambda) - f(\lambda)\|_{\mathbb{L}^1} \xrightarrow[n \rightarrow \infty]{} 0.$$

Remark

If $\epsilon_0 \in \mathbb{L}^2$, then there exists $h_n \rightarrow \infty$ such that $h_n \mathbb{E} \left(|\epsilon_0|^2 \left(1 \wedge \frac{h_n}{n} |\epsilon_0|^2 \right) \right) \xrightarrow[n \rightarrow \infty]{} 0$ holds.

This theorem is true for a fixed design X . But a quick look to the proof of this theorem suffices to see that:

$$\lim_{n \rightarrow \infty} \sup_{\lambda \in [-\pi, \pi]} \mathbb{E} \left(|f_n^*(\lambda) - f(\lambda)| \mid X \right) = 0, \quad a.s.$$

Corollary (Hannan's theorem + Consistence theorem)

Corollary

Under the assumptions of Hannan's Theorem and the previous theorem (Consistence of C_n), we get:

$$C_n^{-\frac{1}{2}} \left(D(n)(\hat{\beta} - \beta) \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}(0, I_p),$$

where I_p is the $p \times p$ identity matrix.

Consequently, we can obtain confidence regions and tests for β in this dependent context.

Sommaire

- 1 Framework
- 2 Hannan's theorem
- 3 Estimation of the covariance matrix
- 4 Tests and Simulations**
Bibliography

“Fisher” test: Dependent case

$H_0 : \beta_{j_1} = \dots = \beta_{j_{p_0}} = 0$, against $H_1 : \exists j_z \in \{j_1, \dots, j_{p_0}\}$ such that $\beta_{j_z} \neq 0$. If the error process is strictly stationary, we have:

$$C_{n_{p_0}}^{-1/2} \begin{pmatrix} d_{j_1}(n)(\hat{\beta}_{j_1} - \beta_{j_1}) \\ \vdots \\ d_{j_{p_0}}(n)(\hat{\beta}_{j_{p_0}} - \beta_{j_{p_0}}) \end{pmatrix} \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}(0_{p_0 \times 1}, I_{p_0}),$$

Then under H_0 -hypothesis:

$$\begin{pmatrix} Z_{1,n} \\ \vdots \\ Z_{p_0,n} \end{pmatrix} = C_{n_{p_0}}^{-1/2} \begin{pmatrix} d_{j_1}(n)\hat{\beta}_{j_1} \\ \vdots \\ d_{j_{p_0}}(n)\hat{\beta}_{j_{p_0}} \end{pmatrix} \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \mathcal{N}(0_{p_0 \times 1}, I_{p_0}),$$

and we define the following test statistic:

$$\Xi = Z_{1,n}^2 + \dots + Z_{p_0,n}^2.$$

Under the H_0 -hypothesis, $\Xi \xrightarrow[n \rightarrow \infty]{\mathcal{L}} \chi_{p_0}^2$.

One-parameter test

If we have $H_0 : \beta_j = 0$ against $H_1 : \beta_j \neq 0$, for j in $\{1, \dots, p\}$ (“Student” test), under the H_0 -hypothesis:

$$d_j(n)\hat{\beta}_j \xrightarrow[n \rightarrow \infty]{} \mathcal{N}(0, c_{j,j})$$

Then the test statistic is:

$$T_{j,n} = \frac{d_j(n)\hat{\beta}_j}{\sqrt{c_{n,(j,j)}}}$$

Under the H_0 -hypothesis, $T_{j,n} \xrightarrow[n \rightarrow \infty]{} \mathcal{N}(0, 1)$

Choice of h_n

$$C_n = D(n)(X^t X)^{-1} X^t \widehat{\Gamma}_{n, h_n}^* X (X^t X)^{-1} D(n),$$

with:

$$\widehat{\Gamma}_{n, h_n}^* = \left[K \left(\frac{j-l}{h_n} \right) \hat{\gamma}_{j-l}^* \right]_{1 \leq j, l \leq n}$$

For the kernel K , we shall use:

$$\begin{cases} K(x) = 1 & \text{if } |x| \leq 0.8 \\ K(x) = 5 - 5|x| & \text{if } 0.8 \leq |x| \leq 1 \\ K(x) = 0 & \text{if } |x| > 1. \end{cases}$$

This kernel verifies the conditions to apply the consistence theorem. It is close to the rectangular kernel (whose Fourier transform is not integrable). Hence, the parameter h_n can be understood as the number of covariance terms that are necessary to obtain a good approximation of Γ_n . To choose its values, we shall use the graph of the empirical autocovariance of the residuals.

Example

We first simulate (Z_1, \dots, Z_n) according to the $AR(1)$ equation $Z_{k+1} = \frac{1}{2}(Z_k + \eta_{k+1})$, where:

- Z_1 is uniformly distributed over $[0, 1]$
- $(\eta_i)_{i \geq 2}$ is a sequence of i.i.d. random variables with distribution $\mathcal{B}(1/2)$, independent of Z_1 .

Let us define:

$$\epsilon_i = F_{\mathcal{N}(0, \sigma^2)}^{-1}(Z_i).$$

By construction, ϵ_i is $\mathcal{N}(0, \sigma^2)$ -distributed (but the sequence $(\epsilon_i)_{i \geq 1}$ is not a Gaussian process). For the simulations, σ^2 is chosen equal to 25.

First model simulated:

$$Y_i = \beta_0 + \beta_1(i^2 + X_i) + \epsilon_i, \quad \forall i \in \{1, \dots, n\}$$

with $(X_i)_{i \geq 1}$ a gaussian $AR(1)$ process (the variance is equal to 9), independent of the process $(\epsilon_i)_{i \geq 1}$.

We test $H_0: \beta_1 = 0$, against $H_1: \beta_1 \neq 0$, for different choices of n and h_n .

- $\beta_0 = 3$.
- Under H_0 , the same Fischer test is carried out 2000 times. Then we look at the frequency of rejection of the test (under H_0), that is to say the estimated level of the test (we want an estimated level close to 5%).

- Case $\beta_1 = 0$ and $h_n = 1$ (no correction):

n	200	400	600	800	1000
Estimated level	0.203	0.195	0.183	0.205	0.202

Here, since $h_n = 1$, we do not estimate any of the covariance terms. The result is that the estimated levels are too large. The test will reject the null hypothesis too often.

The parameter h_n may be chosen by analyzing the graph of the empirical autocovariances. For this example, the shape of the empirical autocovariance suggests to keep only 4 terms. This leads to choose $h_n = 5$.

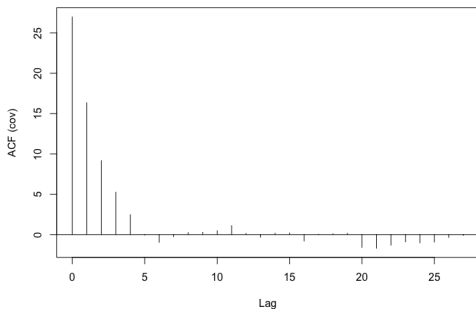


Figure : Empirical autocovariances of the residuals.

- Case $\beta_1 = 0$, $h_n = 5$:

n	200	400	600	800	1000
Estimated level	0.0845	0.065	0.0595	0.054	0.053

As suggested by the graph of the empirical autocovariances, the choice $h_n = 5$ gives a better estimated level than $h_n = 1$. If $n = 2000$ and $h_n = 7$, the estimated level is around 0.05.

- Case $\beta_1 = 0.00001$, $h_n = 5$:

In this example, H_0 is not satisfied. We perform the same tests as above ($N = 2000$) to estimate the power of the test.

n	200	400	600	800	1000
Estimated power	0.1025	0.301	0.887	1	1

As one can see, the estimated power is always greater than 0.05, as expected. Still as expected, the estimated power increases with the size of the samples. As soon as $n = 800$, the test always rejects the H_0 -hypothesis.

Second model

$$Y_i = \beta_0 + \beta_1(\log(i) + \sin(i) + X_i) + \beta_2 i + \epsilon_i, \quad \forall i \in \{1, \dots, n\}$$

We test $H_0: \beta_1 = \beta_2 = 0$ against $H_1: \beta_1 \neq 0$ or $\beta_2 \neq 0$. The coefficient β_0 is equal to 3, and we use the same simulation scheme as above.

- Case $\beta_1 = \beta_2 = 0$ and $h_n = 1$ (no correction):

n	200	400	600	800	1000
Estimated level	0.348	0.334	0.324	0.3295	0.3285

As for the first simulation, if $h_n = 1$ the test will reject the null hypothesis too often.

As suggested by the graph of the estimated autocovariances, it suggests to keep only 5 terms of covariances. This leads to choose $h_n = 6.25$.

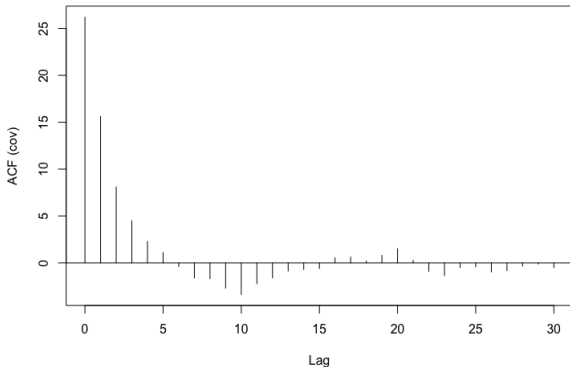


Figure : Empirical autocovariances of the residuals.

- Case $\beta_1 = \beta_2 = 0$, $h_n = 6.25$:

n	200	400	600	800	1000
Estimated level	0.09	0.078	0.066	0.0625	0.0595

Here, we see that the choice $h_n = 6.25$ works well. For $n = 1000$, the estimated level is around 0.06. If $n = 2000$ and $h_n = 6.25$, the estimated level is around 0.05.

- Case $\beta_1 = 0.2$, $\beta_2 = 0$, $h_n = 6.25$:

Now, we study the estimated power of the test.

n	200	400	600	800	1000
Estimated power	0.33	0.5	0.6515	0.776	0.884

As expected, the estimated power increases with the size of the samples, and it is around 0.9 when $n = 1000$.

Perspectives

- To develop a data driven criterion for the coefficient h_n
- Package R for the applications of these results
- To consider the case where p (number of variables) is greater than n (number of observations)

Thank you for your attention !



E. Caron and S. Dede.

Asymptotic distribution of least square estimators for linear models with dependent errors : regular designs.

eprint [arXiv:1710.05963](https://arxiv.org/abs/1710.05963), Oct. 2017.



J. Dedecker, F. Merlevède, and D. Volný.

On the weak invariance principle for non-adapted sequences under projective criteria.

Journal of Theoretical Probability, 20(4):971–1004, 2007.



J. Dedecker and C. Prieur.

New dependence coefficients. examples and applications to statistics.

Probability Theory and Related Fields, 132(2):203–236, 2005.



E. J. Hannan.

Central limit theorems for time series regression.

Probability theory and related fields, 26(2):157–170, 1973.



W. B. Wu.

Nonlinear system theory: Another look at dependence.

Proceedings of the National Academy of Sciences of the United States of America, 102(40):14150–14154, 2005.